

# NS388P-D2

2U 24-Bay NVMe JBOF (2x2 Backplane)



## User Manual

First edition, Jan. 2025

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# 1. Package Checklist

Before the installation of the enclosure, verify that the items below are included in the package:

- A. NS388P enclosure × 1
- B. U.2 SSD drive tray (already installed in NS388P) × 24
- C. U.2 SSD mounting screw × 96
- D. Key for U.2 SSD drive tray × 2
- E. Power cords × 2

**Optional:** (number of host cards and cables will depend on which mode to be used; see section 4)

- F. NP980A-G4 host card
- G. HD mini-SAS (SFF-8644) to HD mini-SAS (SFF-8644) data cables

\* Please check the requirements in **Section 4.**

## 2. Panel Layout

### Front panel



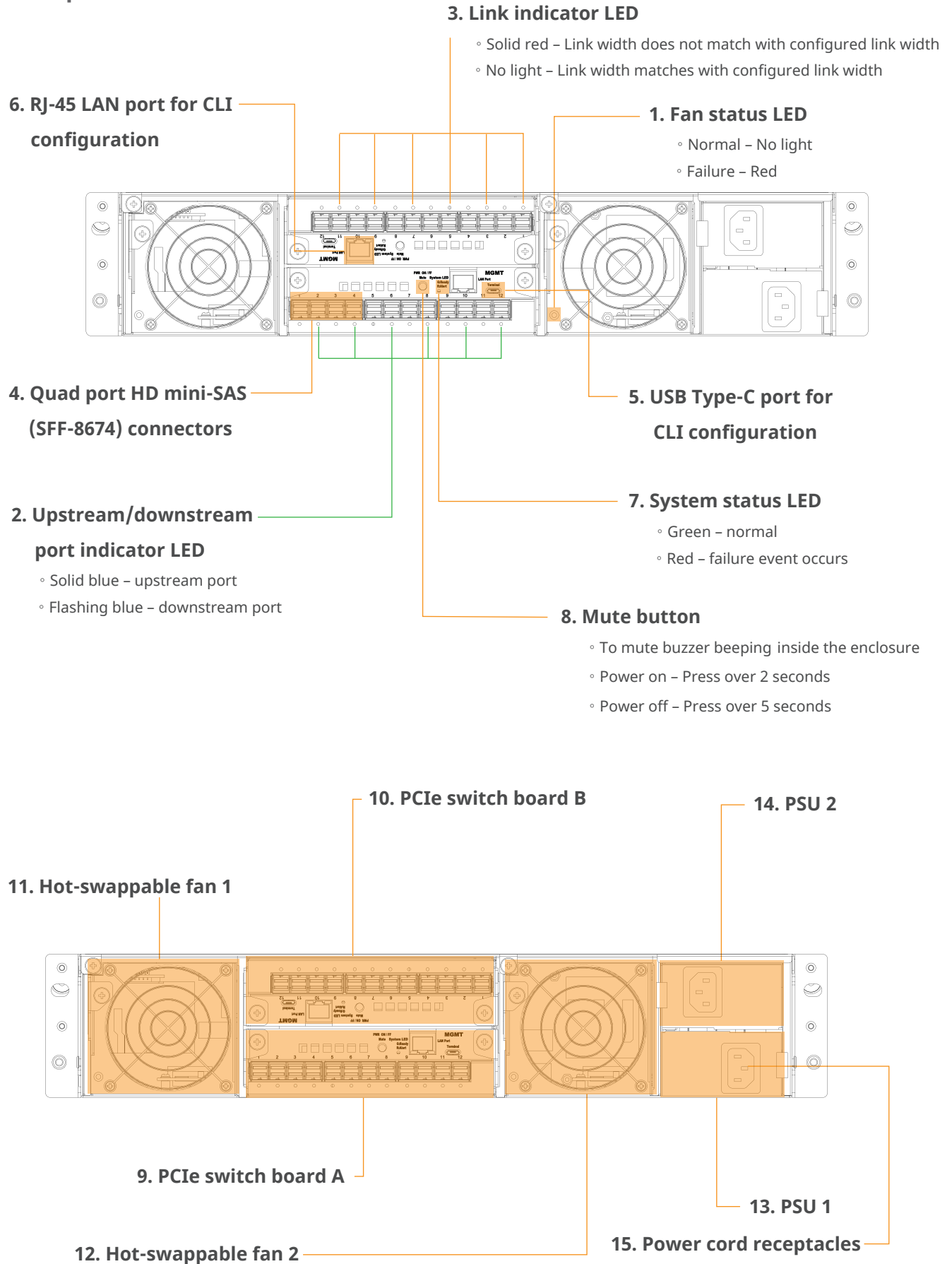
#### 2. U.2 SSD presence LED

- White – Power on
- Flashing white – Drive present, but power is disabled

#### 1. Activity indicator LED

- Flashing blue – Access
- Red – U.2 SSD fails

## Rear panel





## 2.1 Alarm Mute

As any of the followings **(a)** through **(e)** occurs,

**(a) rear cooling fan failure**

**(b) over-temperature within the enclosure**

**(c) voltage abnormal**

**(d) electric current abnormal**

**(e) power supply unit failure**

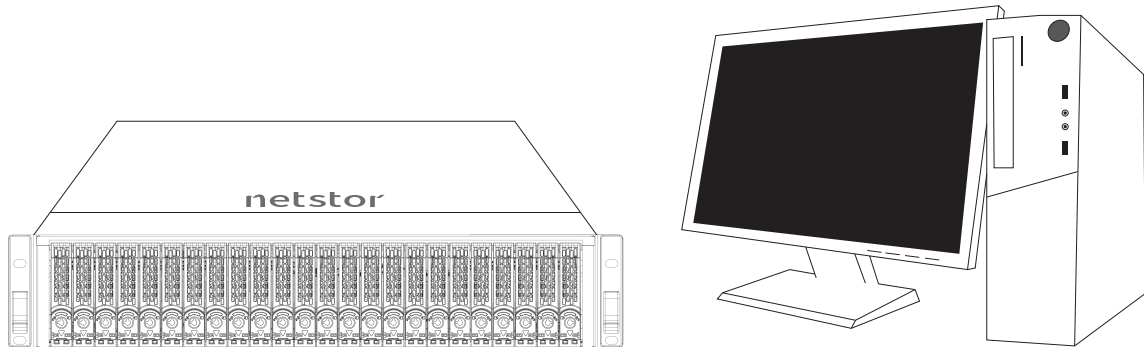
the buzzer on the switch board inside NS388P enclosure will beep. There are two ways to mute the buzzer beeping; either of the two approaches below can be applied to silence the beeping sound:

[1] press PCIe switch board A or B's mute button at rear of the enclosure.

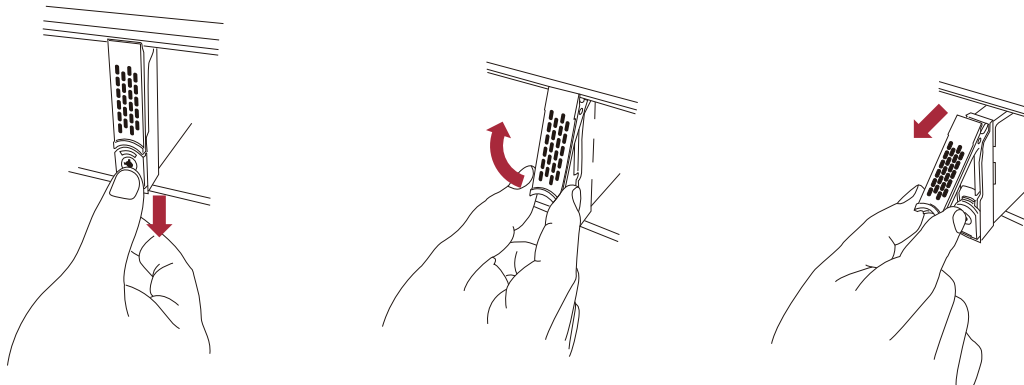
[2] use the 'buz off' command at CLI ([see page 21](#))

### 3. Enclosure Installation

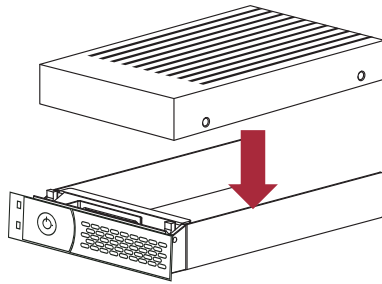
1. Remove the Netstor NS388P enclosure from its packaging, and place the enclosure next to computer, server, or workstation.



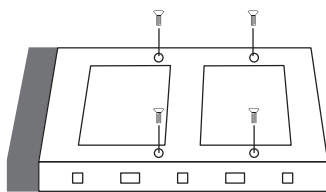
2. Hold one of the U.2 drive trays from the enclosure and push its button downward for the release of the lever until the lever pops out.



3. Place a U.2 drive tray on a flat, level surface, and then attach the 2.5" U.2 NVMe SSD into the tray.

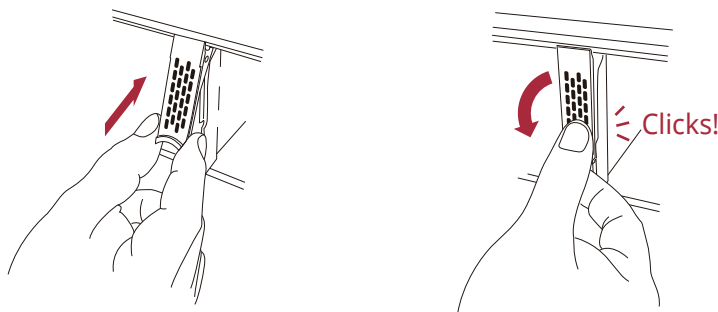


4. Adopt four of the screws provided, and fasten the U.2 NVMe SSD on the tray. Tighten each screw to fasten the U.2 NVMe SSD snugly to the drive tray. Do not tighten the screws overly.



※ You must verify the heads of the four screws are level with the U.2 drive tray while the 2.5" U.2 NVMe SSD is attached to the tray; otherwise, a screw may take hold of the tray from the bottom side and prevent you to pull the tray out of the enclosure.

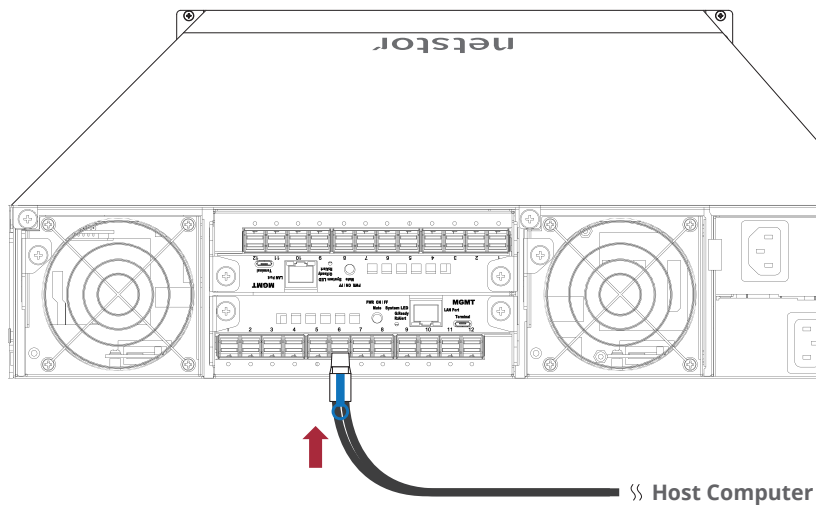
5. Insert the U.2 drive module into the NS388P enclosure correctly until its lever appears to shut, and then press the lever to close until it clicks to ensure that the U.2 drive module is completely within the enclosure.



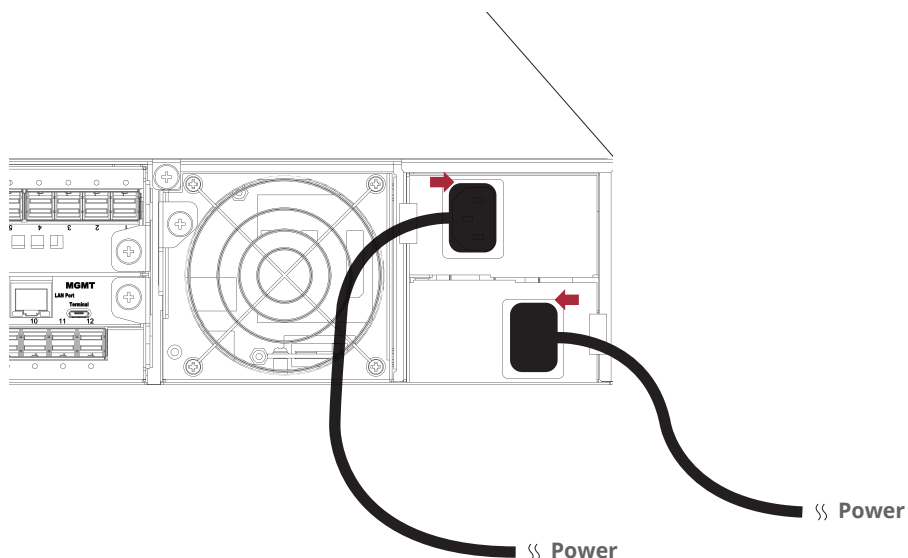
※ Do not force the levers to close while you insert U.2 drive modules into the enclosure. If a lever does not close smoothly, draw out and insert the U.2 drive module again, and then press the lever to close.

6. Repeat steps 2 to 5 for further U.2 NVMe SSD drives.

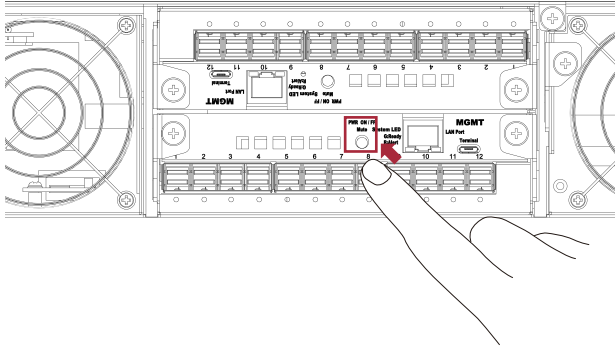
7. Connect NS388P enclosure to NP980A-G4 host card which is installed in server by HD mini-SAS (SFF-8644) to HD mini-SAS (SFF-8644) data cables. Connection types between NS388P and server are shown at [section 4](#) of the user's manual.



8. NS388P enclosure is built with redundant PSU, so connect one end of the two power cords to the two power receptacles at rear of NS388P chassis, and then connect the other end of the two power cords to the power outlets.



9. After the two power cords are connected properly, you can then press the power button for over two seconds at rear of NS388P to power on the Netstor unit, and then power on the server/workstation.



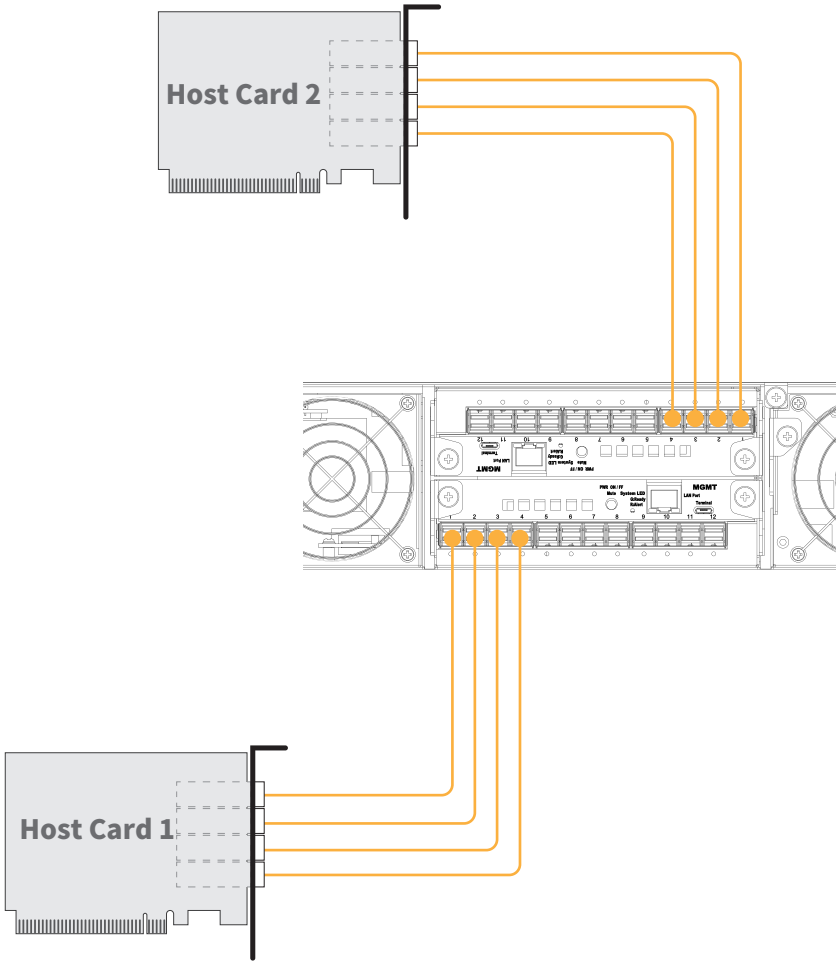
# 4. Switch Mode

Users can use CLI command to set the switch mode. Netstor NS388P NVMe JBOF storage provides 3 modes for selection and application.

## 1. Mode 1

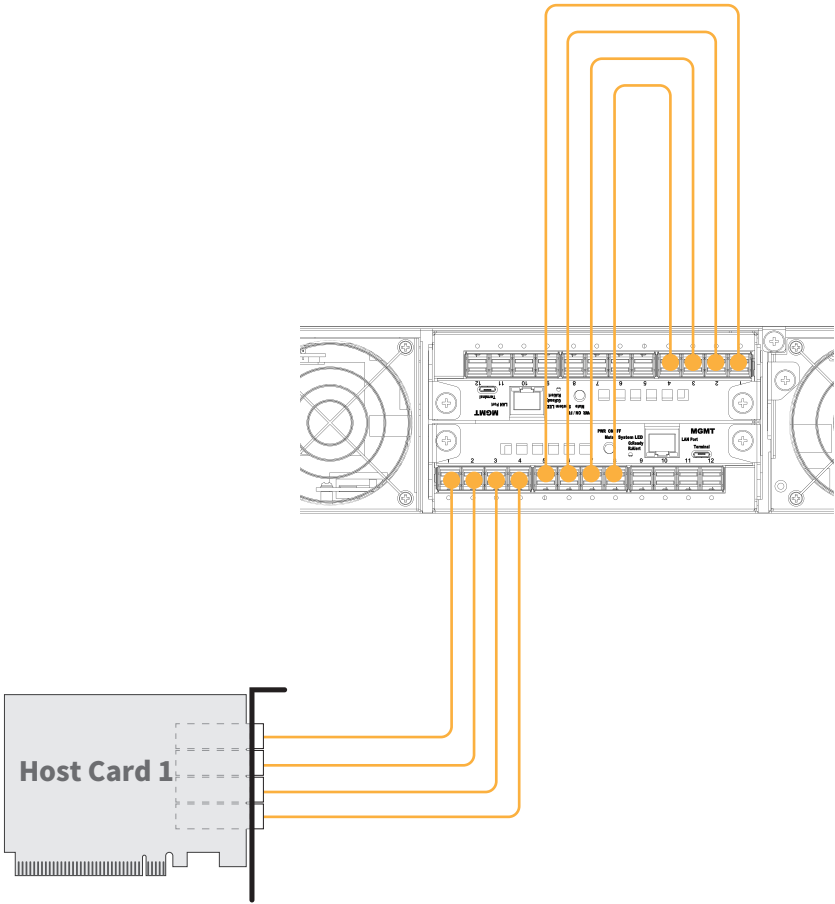
### Connection Type A :

Requirement	Host card ×2, cables ×8
Bandwidth	PCIe 4.0 ×16, 256 Gbps (PCIe switch board A + B)
U.2 SSDs	(1) Host card 1 can access 1st ×2 of dual-port U.2 drives from slot 1 to slot 24 (2) Host card 2 can access 2nd ×2 of dual-port U.2 drives from slot 1 to slot 24



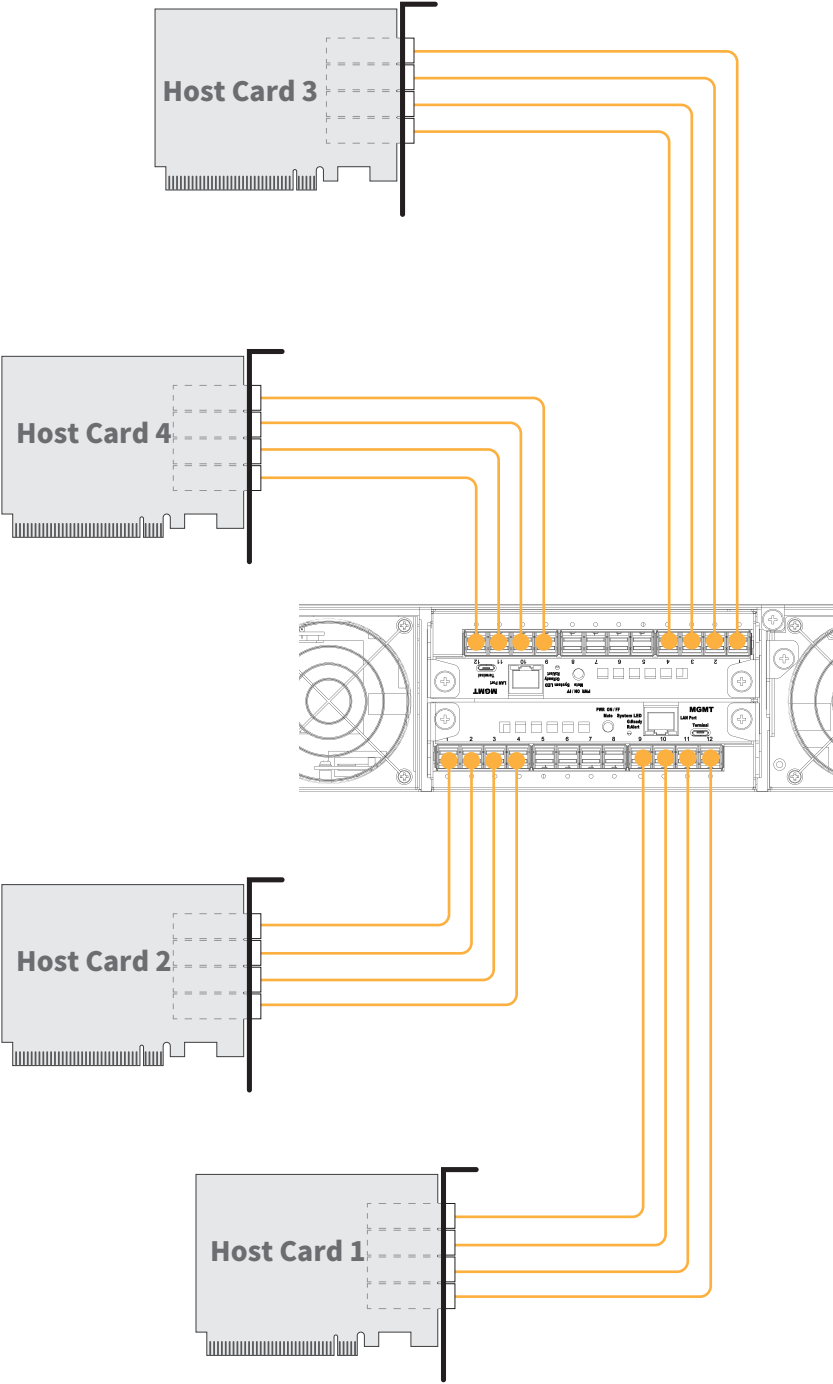
Connection Type B :

Requirement	Host card ×1, cables ×8
Bandwidth	PCIe 4.0 ×16, 256 Gbps (PCIe switch board A + B)
U.2 SSDs	Host card 1 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 1 to slot 24



2. Mode 2

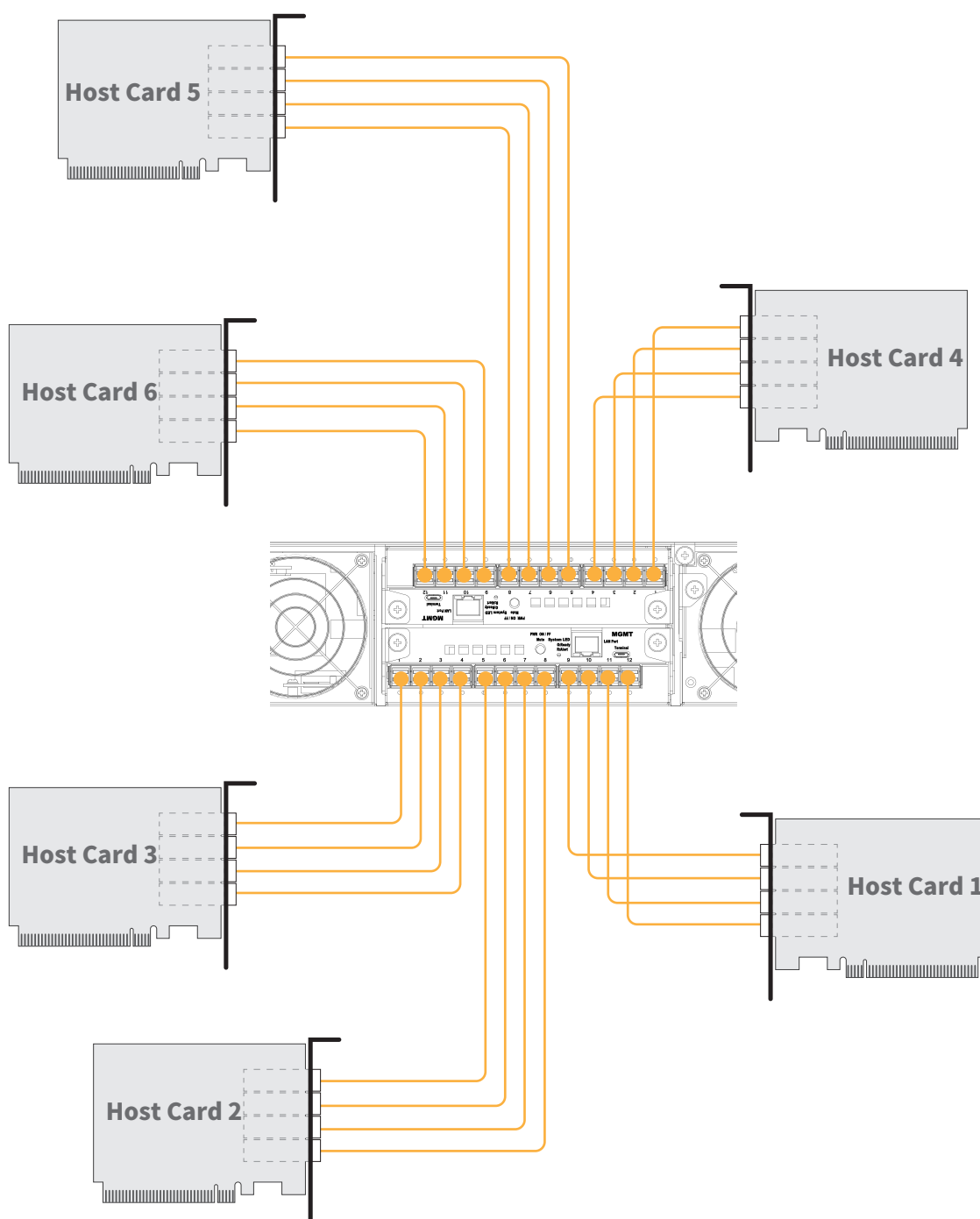
Requirement	Host card ×4, cables ×16
Bandwidth	PCIe 4.0 ×32, 512 Gbps (per PCIe switch board)
U.2 SSDs	(1) Host card 1 & 3 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 1 to slot 12 (2) Host card 2 & 4 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 13 to slot 24





### 3. Mode 3

Requirement	Host card ×6, cables ×24
Bandwidth	PCIe 4.0 ×48, 768 Gbps (per PCIe switch board)
U.2 SSDs	<p>(1) Host card 1 &amp; 4 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 1 to slot 8</p> <p>(2) Host card 2 &amp; 5 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 9 to slot 16</p> <p>(3) Host card 3 &amp; 6 can access 1st and 2nd ×2 of dual-port U.2 drives from slot 17 to slot 24</p>



## 5. CLI Manager

Users can use the Command Line Interface (CLI) to manage the NVMe controller functions. The CLI is useful in environment where a graphical user interface (GUI) is not available.

NS388P NVMe JBOF enclosure uses USB Type-C port as the serial port interface. Please use USB Type-A to USB Type-C cable to connect between NS388P's switch controller board and server; the operation system will detect a new USB-to-Serial COM Port. And use this serial port to configure the switch controller.

Windows 10 & later versions, and Linux operating systems have already integrated the driver for the USB port at NS388P.

### **USB port location :**

#### **Establish the Connection by USB Port**

The CLI function can be managed by using an ANSI/VT-100 compatible terminal emulation program. The program installation procedure must be done before proceeding to the CLI function. Whichever terminal emulation program is used, it must support the XMODEM file transfer protocol.

#### **Start up VT100 Screen**

By connecting a VT100 compatible terminal or a computer operating in an equivalent terminal emulation mode, all CLI administration functions can be executed by the VT100 terminal.

There are a wide variety of Terminal Emulation packages; most of them are very similar. The following setup procedure is an example from VT100 Terminal in Windows 10 operating system using the Tera Term tool.

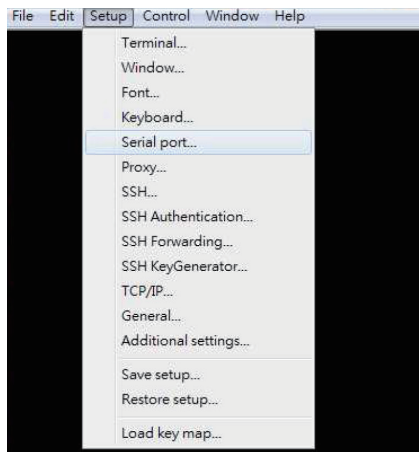
※ **Notice :** Tera Term is a VT100 Terminal Emulation program which is an open-source, free, software implemented, Terminal Emulator tool.

The Tera Term needs to be downloaded; here is the reference site:

<https://tera-term.en.lo4d.com/>

**Step 1.** Install and launch Tera Term program.

**Step 2.** To ensure proper communication between NS388P NVMe JBOF switch controller and the VT100 Terminal emulation, please configure the VT100 Terminal emulation settings to the values as below:



For "**Port**", select **COM3**.

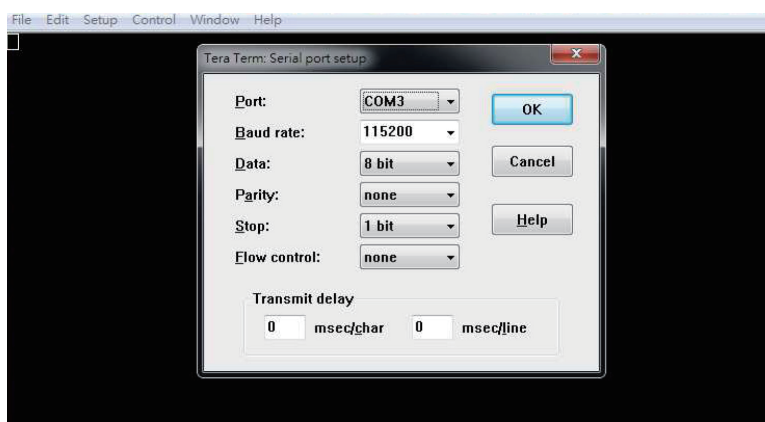
(COM3 is the example; actual COM number will depend on the COM port that is used on the host computer)

For "**Baud rate**", select **115200**.

For "**Data**", select **8 bit**. For "**Parity**", select **none**.

For "**Stop**", select **1 bit**. For "**Flow control**", select **none**.

Click **OK** when the selection is finished.

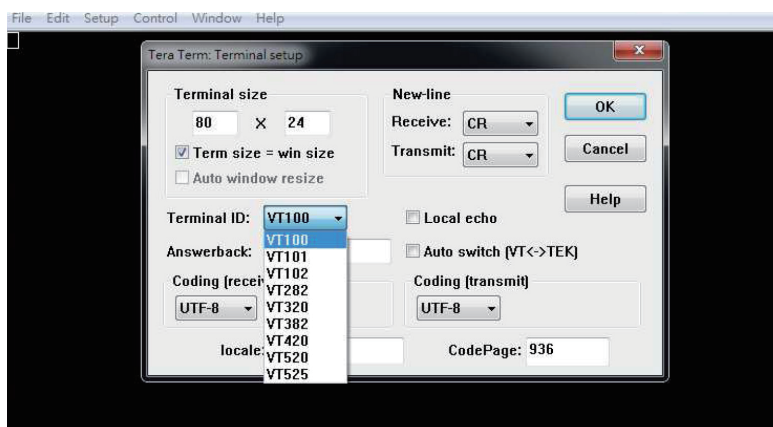


**Step 3.** Select the Terminal emulation type, please go to the Terminal section as shown below:



For “**Terminal ID**”, select **VT100**.

Click **OK** when the selection is finished.



### By RJ-45 LAN Ethernet port

The RJ-45 LAN Ethernet port at rear of NS388P is another way to be used as the serial port interface. Use an Ethernet cable to connect between the RJ-45 port at NS388P and the RJ-45 port at server.

**Step 1.** Click on “**File**” at the top menu bar at Tera Term, and then select “**New connection**”.

**Step 2.** For the item of Host, please key in the default IP address: 192.168.100.20. And for the item of Service, please check “**Telnet**”, and then click on “**OK**” to create the Telnet connection.

## CLI Command

This section provides detailed information about NS388P NVMe JBOF enclosure's CLI function. For all the commands, please type in lower case.

Function	Command	Syntax
Show list of commands	<a href="#">help</a>	help [enter]
Ethernet IP configuration	<a href="#">eth</a>	eth [enter]
Set Ethernet MAC address	<a href="#">setmac</a>	setmac [enter]
Update controller board PCIe switch's firmware	<a href="#">fdl</a>	fdl [fw / mcu] [enter]
Show environmental info (temp, fan, voltage) on NS388P NVMe JBOF enclosure	<a href="#">lsd</a>	lsd [enter]
NS388P enclosure power on/off	<a href="#">syspwr</a>	syspwr [on] / [off] [enter]
Control the buzzer on switch controller board	<a href="#">buz</a>	buz [en] / [dis] / [on] / [off] [enter]
Control the power of each U.2 NVMe drive slot	<a href="#">ssdpwr</a>	ssdpwr [Slot No.] [on or off] [enter]
To reset each U.2 NVMe SSD	<a href="#">ssdrst</a>	ssdrst [Slot No.] [enter]
Ethernet DHCP function	<a href="#">dhcp</a>	dhcp [on] / [off] [enter]
Set PWRDIS for slot's pin3 level to high or low	<a href="#">pwrdis</a>	pwrdis [Slot No.] [h / l] [enter]
Set configuration mode for switch controller board	<a href="#">setmode</a>	setmode [Mode No.] [enter]
Show configuration mode for each switch controller board	<a href="#">showmode</a>	showmode [enter]
Show controller firmware version on switch controller board	<a href="#">ver</a>	ver [enter]
Reset switch controller board	<a href="#">reset</a>	reset [enter]
Dump NVMe JBOF enclosure information	<a href="#">sysinfo</a>	sysinfo [enter]
Show link status for USP/DSP and slot	<a href="#">showport</a>	showport [enter]

## help command

The command provides a list of all commands the user can use for NS388P, also giving a brief description of the supported commands.

The help command can be used to get the detailed information about the CLI commands' summary. Both switch controller boards will show the same list result.

**Syntax:** JBOF > help [enter]

```
File Edit Setup Control Window KanjiCode Help
Cmd Help Menu
syspwr :
  Write JBOF enclosure power control.
  - Usage: syspwr [on|off]

eth :
  Set Ethernet IP Configuration.
  - Usage: eth <ipaddr(*)> <subnet(*)> <gateway(*)>

dhcp :
  Enable DHCP.
  - Usage: dhcp <on|off>

setmac :
  Set Ethernet MAC address.
  - Usage: setmac <xx:xx:xx:xx:xx:xx>

fdi :
  Xnode download image.
  - Usage: fdi <fw|mcu>
  - fw : update fw into switch.
  - mcu : update on-board mcu fw.

lsd :
  Show environmental conditions information.
  - Usage: lsd

ssdpwr :
  slot power control.
  - Usage: ssdpwr [[<slot(0)|all>] <on|off>]
  - slot(0) : slot number should be 1 ~ 24

ssdrst :
  Reset slot.
  - Usage: ssdrst <slot(0)|all> [channel(C)]
  - slot(0) : slot number should be 1 ~ 24
  - channel(C) : channel should be a or b
  - Ex: ssdrst 1
  - Ex: ssdrst 1 a
  - Ex: ssdrst all
  - Ex: ssdrst all a

pwrdis :
  Set pwrdis in slot pin3 level to high/low.
  - Usage: pwrdis [[<slot(0)|all>] <h/l>] (C)]
  - slot(0) : slot number should be 1 ~ 24
  - h(C) : disable SSD power
  - l(C) : enable SSD power
  - Ex : pwrdis all h
  - Ex : pwrdis 1 h

showport :
  Show link status for USP/DSP and slot.
  - Usage: showport

showmode :
  Show mode information of Switchtec port bifurcation.
  - Usage: showmode

setmode :
  Set bifurcation mode of switch controller board.
  - Usage: setmode <mode(0)>
  - mode(0) : mode number should be 1 ~ 7
```

## eth command

Ethernet IP configuration.

**Syntax:** JBOF > eth [enter]

```
Cmd>eth
=====
Physical Address . . . . . : 84-81-D2-8E-22-23
Ethernet Link Status . . . . . : Up
IP Address . . . . . : 192.168.100.200
Subnet Mask . . . . . : 255.255.255.0
Gateway . . . . . : 192.168.100.253
MTU . . . . . : 1500
DHCP . . . . . : OFF
=====
```

[↪ CLI Command List](#)

## setmac command

Set Ethernet MAC (Media Access Control) address.

**Syntax:** JBOF > setmac [enter]

```
Cmd>setmac 00:11:22:33:44:55
MacAddress[0] 0
MacAddress[1] 11
MacAddress[2] 22
MacAddress[3] 33
MacAddress[4] 44
MacAddress[5] 55
Set MAC - save configuration ok
```

[↪ CLI Command List](#)

## fdl command

Update switch controller board's PCIe switch configuration firmware or MCU firmware.

**Syntax:** JBOF > fdl sw [enter]

or

**Syntax:** JBOF > fdl mcu [enter]

```
Cmd>fdl fw
=====
Xmodem upload a new firmware image to flash
=====
Use Q Or q to quit Download
Send data using the -Xmodem- protocol from terminal emulator now!
```

After executing the fdl sw command, click **File** on Tera Term's top menu, select **Transfer**, select **XMODEM**, and select **Send**. Browse to the PCIe switch firmware file, and click OK to proceed and complete the firmware update.

↪ CLI Command List

## lsd command

The command shows environmental information (temperature, fan, voltage) on NS388P NVMe JBOF system.

**Syntax:** JBOF > lsd [enter]

```
Cmd>lsd
Thermal:
  Switch Temperature : 39 degree
  Board Temperature : 31 degree
BackPlane Temperature 1: 30 degree
BackPlane Temperature 2: 29 degree
PSU1 Temperature 1: 32 degree
PSU1 Temperature 2: 32 degree
PSU2 Temperature 1: 29 degree
PSU2 Temperature 2: 28 degree
Fans Speed:
  Switch Fan : 6663 rpm
  Enclosure Fan 1 : 4225 rpm
  Enclosure Fan 2 : 4132 rpm
  PSU1 Fan : 6112 rpm
  PSU2 Fan : 6208 rpm
Current Sensors:
  PSU1 Current : 2476 mA
  PSU2 Current : 3253 mA
Voltage Sensors:
Board 0.84DV Voltage : 847 mV
Board 0.84AV Voltage : 871 mV
Board 1.8V Voltage : 1850 mV
Board 12V Voltage : 12266 mV
BackPlane 3.3V Voltage : 3440 mV
BackPlane 1.8V Voltage : 1776 mV
PSU1 12V Voltage : 12333 mV
PSU2 12V Voltage : 12308 mV
```

↪ CLI Command List



## syspwr command

NS388P enclosure power on & power off.

**Syntax:** JBOF > syspwr [on] / [off] [enter]

```
Cmd>syspwr on
```

[↪ CLI Command List](#)

## buz Command

The command is for controlling the buzzer on switch controller board.

**Syntax:** JBOF > buz [en] / [dis] / [on] / [off] [enter]

[en]: enable the buzzer function for all time

[dis]: disable the buzzer function for all time

[on]: allow buzzer to beep for one time

[off]: mute the buzzer beeping

```
Cmd>buz
Buzzer status:disable
Cmd>buz on
OK, turn on buzzer
Cmd>buz off
OK, turn off buzzer
Cmd>buz en
OK, enable buzzer
Cmd>buz dis
OK, turn off buzzer
OK, disable buzzer
```

[↪ CLI Command List](#)

## ssdpwr command

The command is for controlling the power of each U.2 NVMe drive slot.

**Syntax:** JBOF > ssdpwr [Slot No.] [on or off] [enter]

```
Cmd>ssdpwr 1 off
Slot 01 turn off success.
```

[↪ CLI Command List](#)

## ssdrst command

Reset each U.2 NVMe SSD.

**Syntax:** JBOF > ssdrst [Slot No.] [enter]

```
Cmd>ssdrst 1
Reset con 1 success
```

[↪ CLI Command List](#)

## dhcp command

Ethernet DHCP function.

**Syntax:** JBOF > dhcp [on] / [off] [enter]

```
Cmd>dhcp on
Set Ethernet - save configuration ok
Cmd>eth
=====
Physical Address . . . . .
Ethernet Link Status
```

[↪ CLI Command List](#)

## pwrdis command

Set PWRDIS for U.2 drive slot's pin3 level to high or low.

**Syntax:** JBOF > pwrdis [Slot No.] [h/l] [enter]

```
Cmd>pwrdis 1 h
Set slot 1 pwrdis level to high success.
```

[↪ CLI Command List](#)

## showport command

The command shows link speed and link width information on all U.2 NVMe drive slots.

**Syntax:** JBOF > showport [enter]

```
Board Position: BOTTOM
NVMe Slot-----
Slot01: present Yes, speed 04, width 02, partition 02
Slot02: present No, speed 01, width 00, partition 02
Slot03: present No, speed 01, width 00, partition 02
Slot04: present No, speed 01, width 00, partition 02
Slot05: present No, speed 01, width 00, partition 02
Slot06: present No, speed 01, width 00, partition 02
Slot07: present No, speed 01, width 00, partition 02
Slot08: present No, speed 01, width 00, partition 02
Slot09: present No, speed 01, width 00, partition 01
Slot10: present No, speed 01, width 00, partition 01
Slot11: present No, speed 01, width 00, partition 01
Slot12: present Yes, speed 04, width 02, partition 01
Slot13: present No, speed 01, width 00, partition 01
Slot14: present No, speed 01, width 00, partition 01
Slot15: present No, speed 01, width 00, partition 01
Slot16: present No, speed 01, width 00, partition 01
Slot17: present No, speed 01, width 00, partition 00
Slot18: present No, speed 01, width 00, partition 00
Slot19: present No, speed 01, width 00, partition 00
Slot20: present No, speed 01, width 00, partition 00
Slot21: present No, speed 01, width 00, partition 00
Slot22: present No, speed 01, width 00, partition 00
Slot23: present No, speed 01, width 00, partition 00
Slot24: present No, speed 01, width 00, partition 00
Ext. Slot-----
Con. 01: speed 04, width 16, max_width = 16, Type: USP, partition 00
Con. 02: speed 01, width 00, max_width = 16, Type: USP, partition 01
Con. 03: speed 01, width 00, max_width = 16, Type: USP, partition 02
```

↪ CLI Command List

## setmode command

The command is for setting configuration mode for switch controller board.

**Syntax:** JBOF > setmode [1] / [2] / [3] / [4] / [5] / [6] [enter]

[1]: set for mode 1

[2]: set for mode 2

[3]: set for mode 3

[4]: set for mode 4

[5]: set for mode 5

[6]: set for mode 6

```
Cmd>setmode 4
Set bifurcation mode 4.
Need to reset controller to take effect.
```

[↪ CLI Command List](#)

## showmode command

The command shows configuration mode for each switch controller board.

**Syntax:** JBOF > showmode [enter]

```
Cmd>showmode
Board Position: BOTTOM
Controller mode 6
Board Position: TOP
Controller mode 6
```

[↪ CLI Command List](#)

## ver command

The command shows controller firmware version on switch controller board.

**Syntax:** JBOF > ver [enter]

```
Cmd>ver
S/N      : M40042109010001
Company  :
Model    : Gen4 24 Bays NVMe JBOF
Version  : 0.0.4      Date : Aug 24 2021 17:10:45
BP Type  : x2 backplane
Cfg Rev  : 1
Ctrl status : Master
=====
Switchtec Firmware Revision Information:-
=====
```

[↩ CLI Command List](#)

## reset command

Reset the switch controller board.

**Syntax:** JBOF > reset [enter]

```
Cmd>reset
System Reset...
Cmd>
```

[↩ CLI Command List](#)

## sysinfo command

Show NVMe JBOD enclosure information.

**Syntax:** JBOD > sysinfo [enter]


```
Cmd>sysinfo
=====
ver
=====
S/N      : M40042109010001
Company  :
Model    : Gen4 24 Bays NVMe JBOD
Version  : 0.0.4      Date : Aug 24 2021 17:10:45
BP Type  : x2 backplane
Cfs Rev  : 1
Ctrl status : Master
=====
Switchtec Firmware Revision Information:-
```

 CLI Command List

If you have any questions, please contact your regional distributor,  
or Netstor Technology, Taiwan.



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